NOTE ON THE CRITICAL PATH ANALYSIS FOR A PROJECT WITH A DIVISIBLE ACTIVITY

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In a paper published in JORSA Vol. 13 (1965), W.S. Jewell [2] presented an algorithm for minimizing the total duration of a project with a divisible activity. The mathematical formulation of the problem is as follows:

Minimize t,

subject to
$$v_j - v_i \ge T_{ij}$$
, for $(i,j) \in \overline{D}$, $v_j - v_i - t_{ij} \ge 0$, $t_{ij} \ge 0$, for $(i,j) \in D$, $\sum_{(i,j) \in D} t_{ij} \ge U$, $v_N - v_1 - t = 0$,

where \overline{D} , D, U, T's are given.

He considered the following parametric programming problem P|Q and its dual one D|Q.

$$P|Q:$$
 Minimize $(Qt-\sum_{D}t_{ij})$,

subject to
$$v_j-v_i \ge T_{ij},$$
 for $(i,j) \in \overline{D},$ $v_j-v_i-t_{ij} \ge 0,$ $t_{ij} \ge 0,$ for $(i,j) \in D,$ $t_{ij} \ge 0,$

$$D|Q:$$
 Maximize $\sum_{D} T_{ij} x_{ij}$,

subject to

$$\sum_{\substack{(i,j)\in DU\bar{D}\\(i,j)\in DU\bar{D}}} x_{ij} - \sum_{\substack{(j,i)\in DU\bar{D}\\(j,i)\in DU\bar{D}}} x_{ji} = \begin{cases} Q & (i=1),\\ 0 & (i=2,3,\cdots,N-1),\\ -Q & (i=N), \end{cases}$$

$$x_{ij} \ge 0, \quad \text{for } (i,j)\in \overline{D},$$

$$x_{ij} \ge 1, \quad \text{for } (i,j)\in D.$$

His algorithm consists of two parts, that is, the starting procedure for finding an initial solution of P|Q for a sufficiently large positive Q, and the minimal-flow subroutine for decreasing Q so as to allocate more time to the divisible activity. The latter is one of the primal-dual algorithms. The procedure is terminated when $\sum_{D} t_{ij}$ reaches U, since it is proved in [2] that if an optimal solution of P|Q for some Q, (v_i, t_{ij}, t) , satisfies that $\sum_{D} t_{ij} = U$, then it is also optimal to the original problem.

Here, the author suggests that the usual CPM(critical path method) is directly applicable to the problem without introducing a modified algorithm. We consider the following parametric programming problem $D^*|T$ and its dual one $P^*|T$.

$$D^*|T:$$
 Maximize $\sum_{D} t_{ij}$, subject to $v_j - v_i \ge T_{ij}$, for $(i,j) \in \overline{D}$, $v_j - v_i - t_{ij} \ge 0$, $M \ge t_{ij} \ge 0$, for $(i,j) \in D$, $v_j - v_j = T$.

where M is a sufficiently large positive number.

$$P^*|T$$
: Minimize $[Tq+M\sum_{D}y_{ij}-\sum_{\overline{D}}T_{ij}x_{ij}],$

subject to
$$x_{ij} \ge 0$$
, for $(i,j) \in DU\overline{D}$, $y_{ij} \ge 0$, for $(i,j) \in D$,
$$\sum_{\substack{(i,j) \in DU\overline{D} \\ (i,j) \in DU\overline{D}}} x_{1j} - q = 0$$
,
$$\sum_{\substack{(i,j) \in DU\overline{D} \\ (i,j) \in DU\overline{D}}} x_{ij} - \sum_{\substack{(j,i) \in DU\overline{D} \\ (j,i) \in DU\overline{D}}} x_{ji} = 0 \quad (i=2,3,\cdots,N-1)$$
,
$$\sum_{\substack{(i,j) \in DU\overline{D} \\ (i,j) \in DU\overline{D}}} x_{jN} - q = 0$$
,
$$\sum_{\substack{(i,j) \in DU\overline{D} \\ (i,j) \in DU\overline{D}}} x_{ij} - q = 0$$
, for $(i,j) \in D$.

If T < M, the condition that $M \ge t_{ij} \ge 0$ for $(i,j) \in D$, may be replaced by the condition that $t_{ij} \ge 0$ for $(i,j) \in D$, in $D^*|T$, and y's may be neglected in $P^*|T$. Hence, from Proposition 2.1. of Kurata [4], it is proved that if (v_i, t_{ij}) resp. (x_{ij}, y_{ij}, q) is the optimal solution of $D^*|T$ resp. $P^*|T$ for T < M, $(v_i, t_{ij}, t = T)$ resp. (x_{ij}) is the optimal solution of P|Q = q resp. D|Q = q. Furthermore, $D^*|T$ is equivalent to one of the usual CPM problems:

Maximize
$$\sum_{P} c_{ij} t_{ij}$$
,

subject to
$$v_j-v_i-t_{ij} \ge 0$$
, $D_{ij} \ge t_{ij} \ge d_{ij}$, for $(i,j) \in P$, $v_N-v_1=T$,

when $P = DU\overline{D}$,

$$D_{ij} = \begin{cases} M, & \text{for } (i,j) \in D, \\ T_{ij}, & \text{for } (i,j) \in \overline{D}, \end{cases}$$

$$d_{ij} = \begin{cases} 0, & \text{for } (i,j) \in D, \\ T_{ij}, & \text{for } (i,j) \in \overline{D}, \end{cases}$$

$$c_{ij} = \begin{cases} 1, & \text{for } (i,j) \in D, \\ 0, & \text{for } (i,j) \in \overline{D}. \end{cases}$$

So, we can obtain an optimal solution of the original problem by applying the usual CPM to $D^*|T$. In this case we can easily find a solution of $P^*|T=\infty$, as an initial solution, which is as follows:

$$x_{ij}=0$$
 for $(i,j)\in DU\overline{D}$,
 $y_{ij}=1$ for $(i,j)\in D$,
 $q=0$.

And by decreasing T, less time will be allocated to the divisible activity in the reverse order of Jewell's, and the procedure is terminated when $\sum_{D} t_{ij}$ reaches U.

References

- [1] Ford, L.R. and D.R. Fulkerson, Flows in Networks, Princeton University Press, 1962.
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- [3] Kelley, J.E. "Critical Path Planning and Scheduling: Mathematical Basis," JORSA 9, (1961), 296-320.
- [4] Kurata, R. "Primal Dual Method of Parametric Programming and Iri's Theory on Network Flow Problems," JORSA 7, (1965), 104—144.