

Continuous-time optimal execution in a Markovian environment

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1. Introduction

This study examines a continuous-time optimal execution problem incorporating an exogenous effect called a *Markovian environment*. We derive an optimal execution strategy and show that the Markovian environment described by an Ornstein-Uhlenbeck (OU) process directly affects the execution strategy.

2. Market Model

We assume a (risk-averse) large trader with the risk-aversion parameter $\gamma > 0$ in a financial market. He/she is required to purchase $\Omega (\in \mathbb{R})$ volume of a risky asset in the time window $[0, T]$. Let $Q_t (\in \mathbb{R})$ be the cumulative purchase up to time $t \in [0, T]$ of the large trader. Then, the number of shares remained to purchase at time $t \in [0, T]$ is described as

$$\bar{Q}_t = \Omega - Q_t, \quad (1)$$

with the initial and terminal conditions: $\bar{Q}_0 = \Omega$ and $\bar{Q}_T = 0$. We consider a continuous trading strategy:

$$dQ_t = \dot{Q}_t dt. \quad (2)$$

Here it is assumed that Q_t is continuously differentiable in time $t \in [0, T]$. The execution price of an asset \hat{P} is assumed to follow a *linear price impact model*

$$\hat{P}_t = P_t + \lambda_t \dot{Q}_t, \quad (3)$$

where $P_t (\in \mathbb{R})$ represents the market price of the asset and λ_t the price impact coefficient at time $t \in [0, T]$.

The wealth process, denoted by W_t , evolves as

$$dW_t = -\hat{P}_t dQ_t = -\left(P_t + \lambda_t \dot{Q}_t\right) \dot{Q}_t dt. \quad (4)$$

We define the following market price dynamics:

$$dP_t = \beta_t \lambda_t \dot{Q}_t dt + \mathcal{I}_t dt + dZ_t. \quad (5)$$

$\beta_t \lambda_t \dot{Q}_t$ represents the *permanent impact*. Z_t stands for the effect of *public information* about the economic

situation. We additionally assume that a *Markovian environment*, described by \mathcal{I}_t , affects the asset price.

Remark 1. The Markovian environment can characterize aggregate orders submitted by *small traders*, the effect of *order book imbalance* or *order flow imbalance*, the *difference of the returns* between two assets, and the effect of *trading activity of another asset*, etc.

The mathematically formal setting is as follows. Let $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, \mathbb{P})$ be a filtered probability space, where the processes of \mathcal{I}_t and Z_t are defined as follows:

$$d\mathcal{I}_t = (a_t^{\mathcal{I}} - b_t^{\mathcal{I}} \mathcal{I}_t) dt + \sigma_t^{\mathcal{I}} dB_t^{\mathcal{I}}; \quad (6)$$

$$dZ_t = \mu_t^Z dt + \sigma_t^Z dB_t^Z, \quad (7)$$

where $B_t^{\mathcal{I}}$ and B_t^Z stand for standard Brownian motions with $B_0^{\mathcal{I}} = 0, B_0^Z = 0$. The filtration $\{\mathcal{F}_t\}_{t \geq 0}$ is generated by (B_t^v, B_t^Z) and satisfies the usual conditions: $\mathcal{F}_t = \sigma\{(B_s^{\mathcal{I}}, B_s^Z), s \in [0, t]\}$. We assume that the quadratic co-variation of $B_t^{\mathcal{I}}$ and B_t^Z takes the following form with correlation coefficient $\rho^{Z, \mathcal{I}}$:

$$d\langle B^{\mathcal{I}}, B^Z \rangle_t = \rho^{Z, \mathcal{I}} dt, \quad (8)$$

Here $a_t^{\mathcal{I}}, b_t^{\mathcal{I}}, \mu_t^Z, \sigma_t^{\mathcal{I}}, \sigma_t^Z$ are all deterministic in time t .

If we assume that the information flow accessible for the large trader is carried by the filtration $\{\mathcal{F}_t\}_{t \geq 0}$, the executed volume Q_t of the large trader by time $t \in [0, T]$ is an \mathcal{F}_t -measurable (real-valued) random variable. Let \mathcal{A} be the set of admissible execution strategies. The dynamics of each variable depend on the process of the cumulative purchase (or liquidation) denoted by $Q = \{Q_s\}_{s \in [0, t]}$:

$$dW_t^Q = -\hat{P}_t^Q dQ_t = -\left(P_t^Q + \lambda_t \dot{Q}_t\right) \dot{Q}_t dt;$$

$$dP_t^Q = \beta_t \lambda_t \dot{Q}_t dt + \mathcal{I}_t dt + dZ_t;$$

$$d\bar{Q}_t^Q = -dQ_t = -\dot{Q}_t dt;$$

To simplify the notations, we suppress the superscript Q and simply use the ones defined in the previous de-

scription except for the cases when we should emphasize the time-dependence explicitly.

3. Performance Criteria

3.1. A Hard Constraint

The state, denoted by \mathbf{s}_t , is defined as 4-tuple:

$$\mathbf{s}_t := (W_t, P_t, \bar{Q}_t, \mathcal{I}_t)^\top \in \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} =: S. \quad (9)$$

The utility function of the large trader is assumed to take the form of a Constant Absolute Risk Aversion (CARA) von Neumann-Morgenstern (vN-M) utility function. The utility payoff (or reward) arises only from the terminal wealth at maturity:

$$g_T(\mathbf{s}_T) := \begin{cases} -\exp\{-\gamma W_T\}, & \text{if } \bar{Q}_T = 0; \\ -\infty, & \text{if } \bar{Q}_T \neq 0. \end{cases} \quad (10)$$

We define the (conditional) expected utility at time $t \in [0, T]$ on an execution strategy $Q = \{Q_t\}_{0 \leq t \leq T}$ as

$$V_t^Q := \mathbb{E} \left[g_T(\mathbf{s}_T^Q) \middle| \mathcal{F}_t \right] \quad t \in [0, T]. \quad (11)$$

Let the optimal value from time $t \in [0, T]$ by

$$V_t := \operatorname{ess\,sup}_{Q \in \mathcal{A}} V_t^Q, \quad t \in [0, T]. \quad (12)$$

Then V_t depends on the history or information \mathcal{F}_t only through the (controlled) state: $\mathbf{s}_t \in S$. We denote this functional dependence as follows:

$$V[t, W_t, P_t, \bar{Q}_t, \mathcal{I}_t] := V_t, \quad t \in [0, T]. \quad (13)$$

3.2. A Soft Constraint

We consider a model that a large trader can execute his/her remaining execution volume at the terminal with closing price plus an additive cost χ_T per unit.

The value function at maturity then becomes

$$V[T, \mathbf{s}_T] = -\exp \left\{ -\gamma [W_T - (P_T + \chi_T \bar{Q}_T) \bar{Q}_T] \right\}, \quad (14)$$

and the conditional expected utility at time $t \in [0, T]$

$$V_t^Q := \mathbb{E} \left[-\exp \left\{ -\gamma [W_T - (P_T + \chi_T \bar{Q}_T) \bar{Q}_T] \right\} \middle| \mathcal{F}_t \right]. \quad (15)$$

3.3. HJB Equation

The optimal value function $V_t[\mathbf{s}_t]$ with the terminal condition (14) satisfies, from the dynamic programming principle, the Hamilton–Jacobi–Bellman (HJB)

equation for the optimal execution speed \dot{Q} :

$$\begin{aligned} & \sup_{\dot{Q}_t \in \mathbb{R}} \left[-\left(P_t + \lambda_t \dot{Q}_t \right) \dot{Q}_t \partial_W V + \beta_t \lambda_t \dot{Q}_t \partial_P V - \dot{Q}_t \partial_{\bar{Q}} V \right] \\ & + \partial_t V + (\mathcal{I}_t + \mu_t^Z) \partial_P V + (a_t^I - b_t^I \mathcal{I}_t) \partial_{\mathcal{I}} V + \frac{1}{2} \left\{ (\sigma_t^Z)^2 \partial_{PP} V \right. \\ & \left. + 2\sigma_t^I \sigma_t^Z \rho^{I,Z} \partial_{P\mathcal{I}} V + (\sigma_t^I)^2 \partial_{\mathcal{I}\mathcal{I}} V \right\} = 0, \end{aligned} \quad (16)$$

if we assume the function $V : [0, T] \times S \rightarrow \mathbb{R}$ is in $\mathcal{C}^{1,2}$.

4. Optimal Execution Strategy

Theorem 1. Under a set of regularity conditions,

- the optimal execution speed at time $t \in [0, T]$, denoted as \dot{Q}_t^* , becomes an *affine function* of \bar{Q}_t and \mathcal{I}_t , and *independent* of W_t and P_t :

$$\dot{Q}_t^* = a_t + b_t \bar{Q}_t + c_t \mathcal{I}_t, \quad (17)$$

where a_t, b_t, c_t are deterministic functions of time;

- the optimal value function $V[t, \mathbf{s}_t]$ at time $t \in [0, T]$ is represented as follows:

$$\begin{aligned} V[t, \mathbf{s}_t] = & -\exp \left\{ -\gamma \left[W_t - P_t \bar{Q}_t + G_t \bar{Q}_t^2 + H_t \bar{Q}_t \right. \right. \\ & \left. \left. + M_t \bar{Q}_t \mathcal{I}_t + X_t \mathcal{I}_t^2 + Y_t \mathcal{I}_t + K_t \right] \right\}, \end{aligned} \quad (18)$$

where $G_t, H_t, M_t, X_t, Y_t, K_t$ are deterministic functions of time, and these are assumed to exist as a unique solution of a simultaneous system of ordinary differential equations.

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